Purpose of this Presentation

- Showing the structure of the Event-B modeling notation
- Machines, contexts, and events
- Presenting a small example



Summary of Event-B Modeling Notation

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Model Developments with Event-B

- Event-B is not a programming language (even very abstract)
- Event-B is a notation used for developing mathematical models of discrete transition systems
- Event-B is to be used together with the Rodin Platform

Model Developments with Event-B (cont'd)

- Such models, once finished, can be used to eventually construct:
 - sequential programs,
 - distributed programs,
 - concurrent programs,
 - electronic circuits,
 - large systems involving a possibly fragile environment,
 - etc.
- The <u>underlined statement</u> is an important case.
- In this presentation, we shall construct a small sequential program.





Machines and Contexts

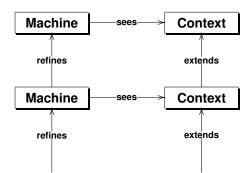
- A model is made of several components
- A component is either a machine or a context:

Machine	Context
variables invariants events variant	sets constants axioms

- Machines and contexts have names
- Such names must be distinct in a given model

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Relationship Between Machines and Contexts



Machines and Contexts (cont'd)

- Contexts contain the static structure of a discrete system (constants and axioms)
- Machines contain the dynamic structure of a discrete system (variables, invariants, and events)
- Machines see contexts
- Contexts can be extended
- Machines can be refined



Visibility Rules (can be Skipped at First Reading)

- A machine can see several contexts (or no context at all).
- A context may extend several contexts (or no context at all).
- A machine implicitly sees all contexts extended by a seen context.
- A machine only sees a context either explicitly or implicitly.

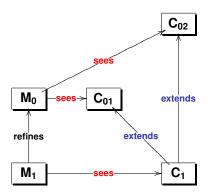
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- A machine only refines at most one other machine.
- No cycle in the "refines" or "extends" relationships.





Example (can be Skipped at First Reading)



- M_0 sees C_{01} and C_{02} explicitly.
- M₁ sees C₁ explicitly.

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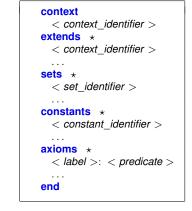
• M_1 sees C_{01} and C_{02} implicitly.

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Explaining Context Sections

- "sets" lists various carrier sets, which define pairwise disjoint types
- The only property we can assume about a set is that it is not empty
- "constants" lists the different constants introduced in the context
- "axioms" defines the main properties of the constants
- axioms can be marked as "theorems" denotes derived properties (to be proved) from previously declared the axioms.

Context Structure



- Sections with "*" might be empty
- All keyword sections are predefined in the Rodin Platform

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context ctx_0 setsDconstantsnfvaxioms $axm1 : n \in \mathbb{N}$ $axm2 : f \in 1..n \rightarrow D$ $axm3 : v \in ran(f)$ $thm1 : n \in \mathbb{N}_1$

- A set *D* is defined in context ctx_0
- Moreover, three constants, *n*, *f*, and *v*, are defined in this context:
 - *n* is a natural number (**axm1**)
 - f is a total function from the interval 1 .. n to the set D (axm2)

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• v is supposed to belong to the range of f (axm3)

• A theorem is proposed: *n* is a positive number (thm1)



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Pictorial Representation of the Context

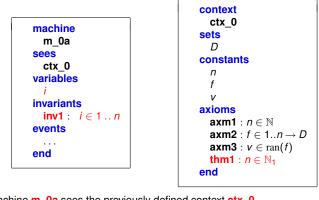
Machine Structure



Explaining Machine Sections

- "variables" lists the state variables of the machine
- "invariants" states the properties of the variables
- Invariants are defined in terms the seen sets and constants
- invariants can be marked as "theorems" which are derivable from previously declared invariants and seen axioms
- "events" defines the dynamics of the transition system (slide 17)
- "variant" is explained later (slide 29)

Machine (and Context) Example

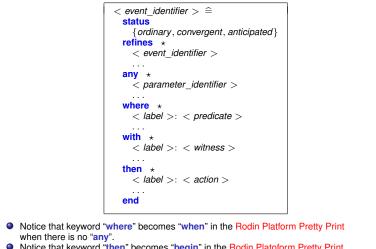


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- Machine m_0a sees the previously defined context ctx_0
- A variable *i* is defined
- *i* is a member of the interval 1 .. *n* (**inv1**)
- events: next slide

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Event Structure



- Notice that keyword "then" becomes "begin" in the Rodin Platoform Pretty Print when there are no "any" and no "where/when".
- Again, all keyword sections are predefined in the Rodin Platform.

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Explaining Event Sections (cont'd)

- "status" is either:
 - ordinary,
 - convergent: it has to decrease the variant (slide 29),
 - anticipated: to be convergent later in a refinement.
- "any" contains the parameters of the event (might be empty)
- "where" (or "when") contains the various guards of the event
- A guard is a necessary condition for an event to be enabled
- Guards can be marked as "theorems" which are derivable from invariants, seen axioms and previously declared guards.
- "actions" see next slide ۲



- An event is a state transition in a discrete dynamic system.
- "refines" contains the name(s) of the refined event(s) (if any)

• Can be skipped at first reading:

- Several refined events are possible in case of a merging refining event concentrating more than one refined event
- Merged events must have the same actions



Explaining Action Section

- An action describes the ways one or several state variables are modified by the occurrence of an event
- An action might be either deterministic or non-deterministic

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Deterministic Action (Example)

• Here is the form of some deterministic actions on variables *x*, *y* and *z*:

$$\begin{array}{ll} x & := x + y \\ y & := y - x - z \end{array}$$

- Notice that *x* and *y* should be distinct.
- Actions are supposed to be "performed" in parallel
- Variables x and y are assigned to x + y and y x z respectively
- Variable z is used but not modified by these actions



Second Form of Non-deterministic Action (Example)

- $x :\in \{x+1, y-2, z+3\}$
- Here x is assigned any value from the set $\{x + 1, y 2, z + 3\}$

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First Form of Non-deterministic Action (Example)

$x, y: | x' > x \land y' < x'$

- On the LHS of operator :|, we have two distinct variables
- On the RHS, we have a, so-called, before-after predicate
- The RHS contains occurrences of x and y (before values) and primed occurrences x' and y' (after values)
- As a result (in this example):
 - x is assigned a value greater than its previous value
 - y is assigned a value smaller than that, x', assigned to x



The Most General Form of an Action

• The second form of non-deterministic action is equivalent to the following first form:

$$x:| x' \in \{x+1, y-2, z+3\}$$

• Likewise, a deterministic action has an equivalent non-deterministic form:

 $x, y: | x' = x + y \land y' = y - x - z$

• The non-det. first form can thus always be assumed (by the tools)



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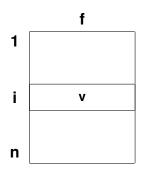


Event Examples of Machine m_0a

• This machine is the model specification of a searching program

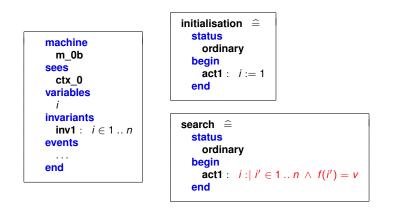
machine m_0a sees ctx_0 variables <i>i</i> invariants	initialisation status ordinary begin act1 : <i>i</i> := 1 end	
inv1 : <i>i</i> ∈ 1 <i>n</i> events end	search ≘ status ordinary any k where	
 Event search assigns to <i>i</i> any value <i>k</i> such that <i>f</i>(<i>k</i>) = <i>v</i>, provided <i>k</i> is in interval 1 <i>n</i> 	$grd1: k \in 1 n$ $grd2: f(k) = v$ then $act1: i := k$ end	
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Pictorial Representation of the State after "search"



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Another Machine m_0b



- The only difference between **m_0a** and **m_0b** is in event **search**
- *i* is assigned non-deterministically a values *i'* such that $i' \in 1 ... n$ and f(i') = v
- Notice that event search has no guard



Explaining Event Sections (cont'd)

- "with" contains the witnesses of a refining event.
- A witness has to be provided in a refining event
 - for each disappearing parameter of the refined event (see m_1a)
 - after value of each disappearing variable.
- The witness for parameter *a* is defined as follows *a* : *P*(*a*) where *P*(*a*) is a predicate involving *a*
- The witness for after value of variable b is defined as follows
 b': P(b') where P(b') is a predicate involving b'
- For a deterministic witness P(x) is x = E (with *E* free of *x*)

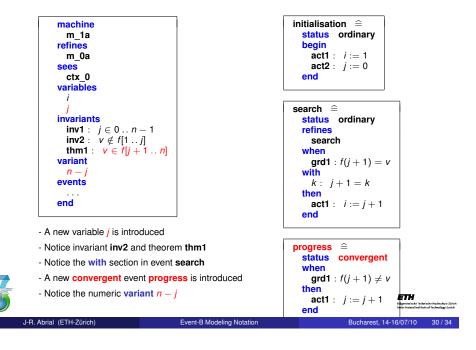
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Variant

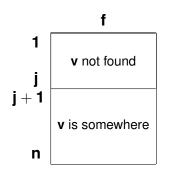
- The variant of a machine is either a natural number expression or a finite set expression
- It has to be present in any machine with convergent events
- A numeric variant must be decreased by all convergent events
- A set variant must be made strictly included in its previous value by all convergent events

Refinement Machine m_1a Refining Machine m_0a

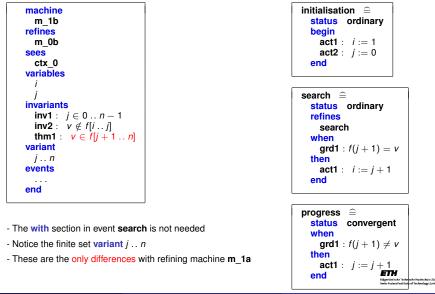




Pictorial Representation of the State



Refinement Machine m_1b Refining Machine m_0b



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Constructing the Final Program

- A sequential program can be constructed from **m_1a** (or **m_1b**)
- This is done by applying a number of event merging rules (NOT DEFINED HERE)
- The application of these rules yields the following program:

i, j := 1, 0; while $f(j + 1) \neq v$ do	initialisation
j := j + 1	progress
end ; i := j + 1	search

yields the	following	program	n:	

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Exercise

 Modify refinement m_1a (or m_1b) in order to obtain the following final program from the same specification m_0a (or m_0b):

i, j := 1, n + 1;initialisation while $f(j-1) \neq v$ do *j* := *j* − 1 progress end; i := j - 1search